

# Discrete Differential Fluids

An Application of Discrete Differential Modeling to Fluid Mechanics

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## Overview

Fluids, fluids, fluids

- geometric interpretation of classical models
- discrete geometric interpretation
  - new integration technique

Bigger Picture:

Discrete Differential Modeling

- don't discretize your PDEs
- uncover their inherent geometry
- *then* discretize this geometry

## Fluid Models (I)

Euler Equations

$$\rho = \text{const} \quad \frac{\partial u}{\partial t} + (u \cdot \nabla)u = -\nabla p + f$$

velocity →  $(u \cdot \nabla)u$  ← pressure  
momentum eq.  
 $\nabla \cdot u = 0$  ← body forces

- inviscid fluids (not viscous)
- incompressible
- non-linear PDE, with linear constraint

## Fluid Models (II)

Navier-Stokes Equations

$$\frac{\partial u}{\partial t} + (u \cdot \nabla)u = -\nabla p + f - \nu \Delta u$$

$$\nabla \cdot u = 0$$

- only change: viscosity
  - coefficient  $\nu$
- loss of total energy during motion

## Algorithm for Simulation

One of many possibilities... (see CFD lit.)

“Stable Fluids” (Stam 99)

- adapted for graphics needs
- regular Eulerian discretization

$$u_{ij}^{*} = u_{ij}^{(t)} + \Delta t f_{ij}^{(t)} - [\Delta t (u \cdot \nabla) u]_{ij}^{(t)}$$

solve Poisson →  $[\Delta t (u \cdot \nabla) u]_{ij}^{(t)}$   
not true velocity divergence →  $\Delta q_{ij} = \nabla \cdot u_{ij}^{*}$

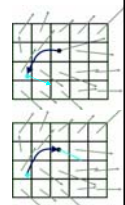
$$u_{ij}^{(t+\Delta t)} = u_{ij}^{*} - \nabla q_{ij}$$

$u_{ij}^{(t)} \in \mathbb{R}^3$

## Implementation Issues

Advection

- discretize? Nah...  $[\Delta t (u \cdot \nabla) u]_{ij}^{(t)}$ 
  - non-linear and nasty
- method of characteristics
  - parcels transported along velocity...
  - let's go backwards in time
    - to know where a “parcel” is coming from
    - need to interpolate velocities
    - and resample them
  - unconditional stability! (large time step)



## What Where?

### Co-located grids

- velocities & pressures at vertices

centered differences

$$\Delta q_{ij} = \nabla \cdot u_{ij}^*$$

$$u_{ij}^* = \nabla q_{ij}$$

- staggered grids



## The Geometry of Fluids

### Euler equations seem clear

- advection + div-free projection ad infinitum
  - numerous follow-up work (Fedkiw *et al.*)
- but what does it mean, geometrically?
  - “total energy” is rather unintuitive
  - is there a notion of momentum preservation?

### Yes

- but of course, we need to massage the PDE
- so as to reveal the geometric structure

## Geometry Revealed

$$\frac{\partial u}{\partial t} + (u \cdot \nabla)u = -\nabla p$$

### Pressure disappears when we take the curl:

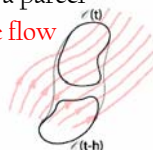
$$\frac{\partial \omega}{\partial t} + \mathcal{L}_u \omega = 0 \quad \omega = \nabla \times u \text{ (vorticity)}$$

$$\text{div}(u) = 0 \quad u \parallel \partial \mathcal{D}$$

- vorticity measures the “spin” of a parcel
- vorticity is “advected” along the flow
- the circulation around any closed loop is constant as it gets advected

$$\Gamma(t) = \oint_{C(t)} u \cdot dl$$

- known as Kelvin’s theorem
- call it preserv. of angular momentum if you want



## Geometry Revealed

### So we know:

Integral of vorticity constant on an advected sheet

### Additionally, $\omega$ defines $u$

- if we ignore complex topology for a moment
- $u = \nabla \times (\Delta^{-1} \omega)$  because  $u$  is divergence free!

Vorticity is the only real variable here and Kelvin’s is a defining property (Navier-Stokes: loss along the way)



## Towards a Proper Discretization

### Domain discretization = simplicial complex

- fluxes through faces for velocity
  - intrinsic (coordinate-free) and eulerian
    - » reminiscent of staggered grids...
- net flux for divergence
  - what comes in...must come out
- flux spin for vorticity
  - Torque created on a “paddle wheel”
- valid for any grid...



## Enter Discrete Exterior Calculus

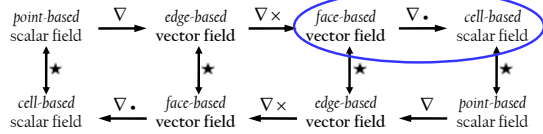
### Need for proper link btw flux, vorticity, div

- hopefully matching differential counterparts
- to create a discrete differential structure
  - i.e., structure-preserving discretization
- Fortunately, that’s DEC
  - we know how to do all that, right??
  - flux = 2-form
  - div = exterior derivative of flux
  - curl =  $\star d \star$  of flux

## Divergence Operator

Simply  $d$  of 2-form

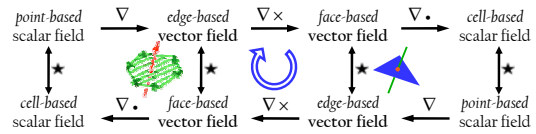
- summing face values of tets
- returning values in tets



## Curl Operator

Curl requires going to the dual

- from faces to dual edges first
- then  $d$  (sum of dual edge values)
- then back onto primal edges



## Laplacian Operator

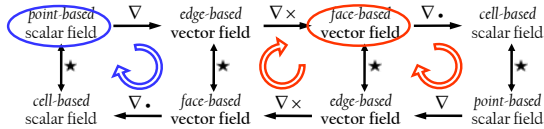
Wait, sum of second partial derivatives... on a PWL field??

- sure, we do it all the time
- link to FE/weak formulation

Try it for 0-forms at home you'll get the cot formula...

How does it work here?

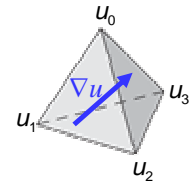
$$\Delta = d \star d \star + \star d \star d$$



## Gradient Operator (for completeness)

Wait, constant per tet, right? (FEM 101)

- yes
- but can be stored as values on edges, as announced



$$u = \sum_i u_i \varphi_i$$

$$\Rightarrow du = \sum_i u_i d\varphi_i = \sum_{e_k=\{i,j\}} (u_i - u_j) \varphi_{e_k}$$

## Integrating Equations of Motion

We have all the computational set-up

- But how do we integrate the motion?

Through preserving important structures?

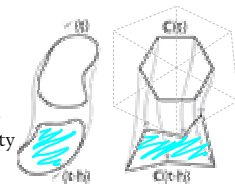
- Circulation/vorticity preservation
- Crucial for visual impact
  - vortices in smoke
  - vortices in liquids



## Discrete Kelvin's Theorem

Simple way to integrate Euler equations:

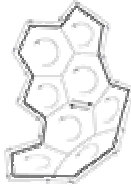
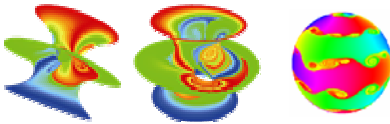
- For each 1-simplex
  - backtrack local loop in current velocity field
  - deduce new circulation
    - i.e., new discrete vorticity
- Find new velocity field
  - simple Poisson equation
    - $u = \nabla_x (\Delta^{-1} \omega)$



## Discrete Kelvin's Theorem

Guarantees circulation preservation  
for any discrete loop

- big loop = union of small ones
- ... even on curved spaces



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## Results

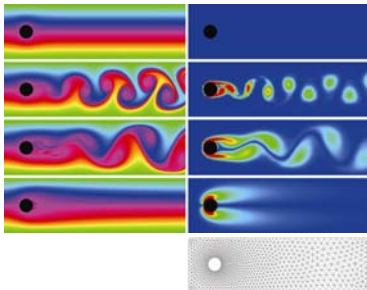
New method

- exact discrete vorticity preservation
- arbitrary simplicial meshes
  - see also paper by Feldman *et al.* this year
- everything is intrinsic
- basic operators very simple (super parse)
- great flows for small meshes!
  - computationally efficient even on coarse mesh
  - no need for millions of vortex particles

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## Channel



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## Smoking Bunny



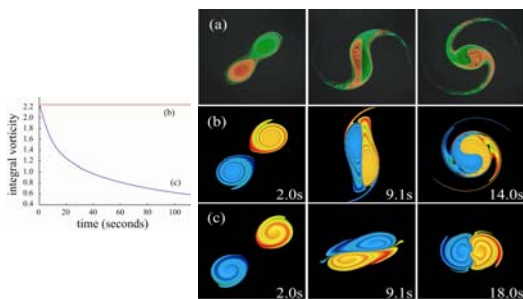
7k vertices, 32k tets; 0.45s  
per frame on PIV (3GHz)



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## Merging Vortices



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## Movie

Discrete, Circulation-Preserving,  
and Stable Simplicial Fluids

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## Take-Home Message

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### Don't Discretize your PDE

- discretize its geometric structures
  - PDEs often hide these structures
- uncover the nature of the variables involved
  - usually, natural locations on mesh
- turn the crank....

### Next

- circles may be the right discrete geometry!
  - conformal geometry